



(19) Europäisches Patentamt
European Patent Office
Office européen des brevets



(11) EP 0 907 083 A1

(12)

EUROPEAN PATENT APPLICATION

(43) Date of publication:
07.04.1999 Bulletin 1999/14

(51) Int Cl. 6: G01N 35/04, G01N 35/00,
B67B 7/02, B65D 39/16

(21) Application number: 98810932.8

(22) Date of filing: 18.09.1998

(84) Designated Contracting States:
AT BE CH CY DE DK ES FI FR GB GR IE IT LI LU
MC NL PT SE
Designated Extension States:
AL LT LV MK RO SI

(30) Priority: 02.10.1997 EP 97117102

(71) Applicant: F. HOFFMANN-LA ROCHE AG
4070 Basel (CH)

(72) Inventors:
• Fassbind, Walter
6340 Baar (CH)
• Schnarwiler, Rolf
6280 Hochdorf (CH)

(74) Representative:
AMMANN INGENIEURS-CONSEILS EN
PROPRIETE INTELLECTUELLE SA BERNE
Schwarztorstrasse 31
3001 Bern (CH)

(54) Automatic handling of sample cups closed with a screwable cap

(57) An apparatus for automatically handling sample cups closed with a screwable cap in a system where in portions of biological samples contained in primary sample tubes have to be automatically pipetted into and from said sample cups. In order to provide very simple and relatively inexpensive means for automatically opening, closing and transporting sample cups the apparatus is characterized in that it comprises a transportable gripper (11) which includes a rotatable gripper tool (21) apt to enter and engage with a recess (35, 36) of said cap (34) to form a connection which can be locked by rotating the gripper tool (21) in a first sense with respect to said sample cup (31) and which can be unlocked by rotating the gripper tool (21) with respect to said sample cup (31) in a second sense opposite to the first.

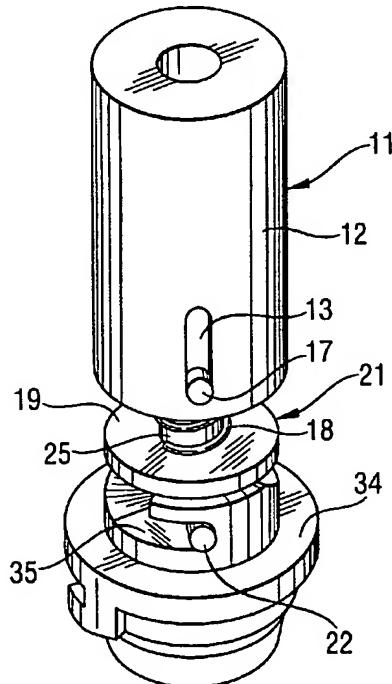


Fig. 1

EP 0 907 083 A1

Description

[0001] The invention concerns an apparatus for automatically handling sample cups closed with a screwable cap in a system wherein portions of biological samples contained in primary sample tubes have to be automatically pipetted into and from said sample cups.

[0002] The invention further concerns a method for automatically handling sample cups closed with a screwable cap in a system wherein portions of biological samples contained in primary sample tubes have to be automatically pipetted into and from said sample cups.

[0003] The invention further concerns a sample cups closed with a screwable cap which is adapted to be used in an apparatus and in a method according to the invention.

[0004] The invention concerns in particular an apparatus, a method and a sample cup of the above mentioned types which is suitable in particular for handling sample cups used in a method for isolating a nucleic acid sample from cell material.

[0005] Such sample cups have to be hermetically closed preferably with a screwable cap in order to ensure that the sample contained therein cannot be contaminated by external agents and also in order to protect laboratory staff from the risk of being contaminated by a pathological sample which may be contained in the sample cup. This applies in general to sample cups used for clinical chemistry tests, and in particular to sample cups used in methods for isolating a nucleic acid sample from cell material.

[0006] According to the prior art the cap of such a sample cup has to be removed and replaced manually with great care in order to allow pipetting operations, e.g. for transferring a portion of a biological sample contained in a primary sample tube can be pipetted into the sample cup, e.g. before a method for isolating a nucleic acid sample from cell material is carried out on a sample contained in a sample cup, or for transferring a nucleic acid sample isolated by such a method into the sample cup.

[0007] The above mentioned manual removal and replacement of the screwable cap of sample cups is a handling which is time consuming and which is not compatible with the increasing need for automatic handling of sample cups in modern automatic sample cup handling apparatuses. There is therefore a need to automatize the removal and replacement of the screwable caps.

[0008] There is moreover a need to transport individual sample cups closed with their respective screwable cap to different positions within the sample cup handling apparatus, e.g. in order to perform different steps of a method for isolating a nucleic acid sample from cell material.

[0009] A first aim of the invention is therefore to provide an apparatus and a method which are suitable for satisfying the above mentioned needs at least individually.

[0010] A second aim of the invention is to provide an apparatus and a method which are suitable for satisfying both above mentioned needs in the most simple and therefore less expensive way.

[0011] A third aim of the invention is to provide a sample cup which is suitable for satisfying the above mentioned needs in the most simple and therefore less expensive way.

[0012] According to a first aspect of the invention the aims of the invention are attained with an apparatus comprising a transportable gripper which includes a rotatable gripper tool apt to enter and engage with a recess of said cap to form a connection which can be locked by rotating the gripper tool in a first sense with respect to said sample cup, and which can be unlocked by rotating the gripper tool with respect to said sample cup in a second sense opposite to the first.

[0013] According to a second aspect of the invention the aims of the invention are attained with an apparatus comprising

a) a sample cup holder having a plurality of chambers, each of which is apt to receive and hold the lower part of a sample cup preventing rotation thereof,

b) a plurality of sample cups, each of which is closed with a removable screwable cap and the lower part of which is inserted in one of said chambers of the sample cup holder,

the outer wall of said cup having a zone the shape of which is apt to cooperate with a corresponding zone of the inner surface of the chamber of the sample cup holder to prevent rotation of the sample cup inserted in said chamber, said screwable cap having a recess located in the top and central part of the cap, said recess comprising a slot which extends along the length axis of the sample cup and which ends in two annular channel segments which extend in opposite angular directions with respect to the length axis of the sample cup,

c) a gripper movable in three orthogonal directions by a transport device, said gripper comprising a rotatable gripper tool which has an end part having a shape and dimensions which match the shape and dimensions of the recess of the cap in such a way that the end part of the gripper tool can enter through the slot of the cap's recess and by rotation enter into and engage the annular channel segments of said recess,

d) a transport device for moving said gripper in said three orthogonal directions and for positioning and rotating said gripper tool of a predetermined angle within said recess of the cap of a sample cup.

[0014] According to a third aspect of the invention the aims of the invention are attained with a method for automatically handling sample cups closed with a screwable cap in a system wherein portions of biological sam-

ples contained in primary sample tubes have to be automatically pipetted into and from said sample cups, said method comprising transporting a sample cup

by means of a transportable gripper which includes a rotatable gripper tool apt to enter a recess of said cap, said transporting being effected by positioning said gripper tool in said recess, by rotating said gripper tool within said recess with respect to said sample cup until it engages and locks into said recess, and by transporting the gripper and thereby the sample cup from a first position to a second position.

[0015] According to a fourth aspect of the invention the first aim of the invention is attained with a method for automatically handling sample cups closed with a screwable cap in a system wherein portions of biological samples contained in primary sample tubes have to be automatically pipetted into and from said sample cups, said method comprising

removing the cap of a sample cup by means of a transportable gripper which includes a rotatable gripper tool apt to enter a recess of said cap, said removing being effected by positioning said gripper tool in said recess, and by rotating said gripper tool within said recess in a first sense with respect to said sample cup, thereby unscrewing the cap and removing it from the sample cup.

[0016] According to a fifth aspect of the invention the first aim of the invention is attained with a method for automatically handling sample cups closed with a screwable cap in a system wherein portions of biological samples contained in primary sample tubes have to be automatically pipetted into and from said sample cups, said method comprising replacing the cap of a sample cup by means of a transportable gripper which includes a rotatable gripper tool apt to enter a recess of said cap, said replacing being effected

by positioning said gripper tool in said recess, and by rotating said gripper tool within said recess in a second sense with respect to said sample cup, said second sense being opposite to said first sense, thereby screwing the cap and replacing it on the sample cup.

[0017] According to a sixth aspect of the invention a sample cup suitable to be used with an apparatus according to the invention is characterized in that it comprises a removable screwable cap which has a recess located in the top and central part of the cap, said recess comprising a slot which extends along the length axis of the sample cup and which ends in two annular channel segments which extend in opposite angular directions

with respect to the length axis of the sample cup, and an outer wall having a zone which is adapted to cooperate with a corresponding zone of the inner surface of a chamber of a sample cup holder in order to prevent rotation of the sample cup when the lower part thereof is inserted in that chamber.

[0018] The main advantage of the apparatus, method and sample cup according to the invention is that they provide very simple and relatively inexpensive means for automatically opening, closing and transporting sample cups.

[0019] Exemplified embodiments of apparatus, method and sample cup according to the invention are described below with reference to the accompanying drawings wherein:

[0020] Fig. 1 shows a perspective view of a transportable gripper 11 which is an essential part of an apparatus according to the invention.

[0021] Fig. 2 shows an exploded view of the gripper 11 in Fig. 1.

[0022] Fig. 3 is a cross-sectional view of the gripper tool 21 of gripper 11 in Figures 1 and 2.

[0023] Fig. 4 is a perspective view of a sample cup 31 according to the invention.

[0024] Fig. 5 is a side view of sample cup 31 in Fig. 4.

[0025] Fig. 6 is a cross-sectional view of sample cup 31 along A-A in Fig. 5.

[0026] Fig. 7 is a plan view of sample cup 31 in Fig. 4.

[0027] Fig. 8 is a perspective view of a sample cup holder 41 holding a plurality of sample cups.

[0028] Figures 9 to 16 illustrate schematically various steps of methods of handling sample cups according to the invention.

[0029] An apparatus according to the invention comprises a transportable and rotatable the gripper 11 of the type described hereinafter with reference to Figures 1 to 3. Transport of gripper 11 is carried out e.g. by an X-Y-Z transport system which enables movement of gripper 11 in 3 directions which are normal to each other.

[0030] Rotation of the gripper is carried out by suitable controlled motor means associated to the latter transport system. The controlled motor means are such that rotation of gripper 11 and thereby of gripper tool 21 is possible in both angular senses, clockwise or in the opposite sense. The controlled motor means include means for measuring variations of the amount of electrical energy associated to rotational movement of the gripper tool. In this way the apparatus is able to detect different states of its operation, e.g. when the gripper tool has engaged the recess of the cap 34 and force should be applied to unscrew cap 34 and remove it from sample cap 31.

[0031] Gripper 11 comprises a housing 12 having a top wall and a side wall which has elongated openings 13 and 13 a (not shown) located on diametrically opposite sides of the side wall of housing 12, a first spring 14, and a gripper tool 21 which has a cylindrical upper part 16 which has a cavity 15 and a bottom wall connected to a shaft 25 which extends along the rotation

axis of the cylindrical upper part 16 and has a lower end 24.

[0031] Pin shaped projections 17 and 17 a radially extend in opposite directions from the side wall of cylindrical upper part 16. Shaft 25 has at its lower end pin shaped projections 22, 23 which radially extend in opposite directions.

[0032] An annular disk 19 is free to glide along shaft 25 between the bottom wall of cylindrical upper part 16 and pin shaped projections 22, 23. Disk 19 is however pressed against projections 22, 23 by a second spring 18 arranged with respect to shaft 25 as shown by Fig. 2.

[0033] In the assembled state of gripper 11 shown by Fig. 1, spring 14 and cylindrical part 16 are so arranged within housing 12 that pin shaped projections 17 and 17 a pass through respective openings 13, 13 a of housing 12, and spring 14 transmits force exerted on it by housing 12 to cylindrical upper part 16. In this way depending on the magnitude of the force applied, cylindrical upper part 16 can move within housing 12 within limits defined by the length of openings 13, 13 a.

[0034] From figures 1-4 and the above description it can be appreciated that when gripper 11 is rotated, gripper tool 21 rotates with it.

[0035] In addition to the above described parts of gripper 11, Figures 1 and 2 show a cap 34 of a sample cup according to the invention.

[0036] As shown by Fig. 1, when gripper tool 21 of gripper 11 holds cap 34 spring 18 presses disk 19 against the top of cap 34, a part of which is held between disk 19 and projections 22, 23 of gripper tool 21, and the projections 22, 23 at the lower end of gripper tool 21 are engaged with recesses 35, 36 of cap 34. In Fig 1 only recess 35 and projection 22 are shown.

[0037] Figures 4 to 7 show in more detail a sample cup 31 according to the invention. Such a sample cup 31 comprises a removable screwable cap 34 which has a recess located in the top and central part of the cap. This recess comprises a slot 37 which extends along the length axis of the sample cup 31 and which ends in two annular channel segments 35, 36 which extend in opposite angular directions with respect to the length axis of the sample cup 31. Sample cup 31 has an outer wall 32 which has a zone 33 the shape of which is adapted to cooperate with the shape of a corresponding zone of the inner surface of a chamber of a sample cup holder in order to prevent rotation of the sample cup 31 when the lower part thereof is inserted in that chamber.

[0038] An essential feature of an apparatus according to the invention is that it comprises a rotatable gripper tool 21 which is configured and dimensioned to enter and engage with a recess 35, 36 of said cap 34 to form a connection which can be locked by rotating the gripper tool 21 in a first sense with respect to said sample cup 31 and which can be unlocked by rotating the gripper tool 21 with respect to said sample cup 31 in a second sense opposite to the first.

[0039] In a preferred embodiment now described with

reference to Fig. 8 an apparatus according to the invention is used to handle a plurality of sample cups 51-69 each of which is inserted in one of a corresponding plurality of chambers of a sample cup holder 41 which has e.g. the shape shown by Fig. 8. For proper operation according to the invention the inner surface of each of said chambers has to have a zone the shape of which is apt to cooperate with zone 33 of the outer wall of sample cup 31 in such a way that when such a sample cup

is inserted in one of the chambers of sample cup holder 41, sample cup 31 is held stationary by said chamber and is not free to rotate around its length axis.

[0040] As can be appreciated from Fig. 8 the sample cups schematically shown therein are of the type described above with reference to Figures 4 to 7. Each of the sample cups 51-69 shown in Fig. 8 is closed with a removable screwable cap and the lower part of which is inserted in one of said chambers of the sample cup holder 41. The outer wall of each of said cups 51-69 has a zone which cooperates with a corresponding zone of the inner surface of the chamber of the sample cup holder 41 to prevent rotation of the sample cup 51-69 inserted in said chamber. The screwable cap of each of sample cups 51-69 has a recess located in the top and central part of the cap, said recess comprising a slot which extends along the length axis of the sample cup and which ends in two annular channel segments which extend in opposite angular directions with respect to the length axis of the sample cup.

[0041] An apparatus according to the invention for the above mentioned use with reference to Fig. 8 comprises a gripper of the type described above with reference to Figures 1-3, that is a gripper like gripper 11 movable in three orthogonal directions by a transport device. Such a gripper comprises a rotatable gripper tool which has an end part having a shape and dimensions which match the shape and dimensions of the recess of the cap of each sample cup in such a way that the end part of the gripper tool can enter through the slot of the cap's recess and by rotation enter into and engage the annular channel segments of said recess. The transport device for moving the latter gripper is suitable for moving it in said three orthogonal directions, and for positioning and rotating the gripper tool of the gripper of a predetermined angle within the recess of the cap of each of the sample cups 51-69.

[0042] A method for holding and transporting sample cups 31 closed with a screwable cap 34 with an apparatus according to the invention in a system wherein portions of biological samples contained in primary sample tubes have to be automatically pipetted into and from said sample cups is now described with reference to Figures 9 to 12. Such a method comprises transporting a sample cup 31 by means of a transportable and rotatable gripper which includes a gripper tool 21 apt to enter a recess 35, 36, 37 of said cap 34, said transporting being effected by positioning said gripper tool 21 in said recess 35, 36, 37; by rotating said gripper tool 21 within

said recess 35, 36, 37 with respect to said sample cup 31 until it engages and locks into said recess 35, 36, 37; and by transporting the gripper tool and thereby the sample cup 31 from a first position to a second position.

[0043] In order to position gripper tool in the recess of cap 34, gripper tool 21 is lowered by the transport means (see Fig. 9) until it contacts the upper surface of cap 34. When that contact is established gripper tool 21 is rotated by the above mentioned controlled motor means while the transport means still exert a gentle downwards force on gripper tool 21. In this way, when the angular position of projections 22, 23 of gripper tool 21 coincides with the angular position of slot 37 of cap 34, the latter projections enter slot 37 and upon further rotation projections 22, 23 engage with annular channel segments 35, 36 of cap 34 (see Fig. 10), and in this way establish a locked connection between gripper tool 21 and cap 34, and thereby between gripper tool 21 and sample cup 31. Figures 11 and 12 illustrate upward and downward transport of sample cup 31 by means of gripper tool 21.

[0044] A method for removing the screwable sample cap 34 of a sample cup 31 with an apparatus according to the invention is now described with reference to Figure 13. Such a method comprises positioning said gripper tool 21 in said recess 35, 36, 37 and rotating said gripper tool 21 within said recess 35, 36, 37 in a first sense with respect to said sample cup 31, thereby unscrewing the cap 34 and removing it from the sample cup 31.

[0045] A method for replacing, i.e. for screwing a screwable sample cap 34 on a sample cup 31 with an apparatus according to the invention is now described with reference to Figures 14 and 15. Such a method comprises positioning said gripper tool 21 in said recess 35, 36, 37 and rotating said gripper tool 21 within said recess 35, 36, 37 in a second sense with respect to said sample cup 31, said second sense being opposite to said first sense, thereby screwing the cap 34 and replacing it on the sample cup 31.

[0046] Figure 16 illustrates how cap 34 and thereby sample cup 31 is released from gripper tool 21.

Claims

- An apparatus for automatically handling sample cups closed with a screwable cap in a system wherein portions of biological samples contained in primary sample tubes have to be automatically pipetted into and from said sample cups, said apparatus comprising
a transportable gripper (11) which includes a rotatable gripper tool (21) apt to enter and engage with a recess (35, 36) of said cap (34) to form a connection which can be locked by rotating the gripper tool (21) in a first sense with respect to said sample cup (31) and which can be unlocked by rotating the gripper tool (21) with respect to said sample cup (31) in

a second sense opposite to the first.

- An apparatus for automatically handling sample cups closed with a screwable cap in a system wherein portions of biological samples contained in primary sample tubes have to be automatically pipetted into and from said sample cups, said apparatus comprising
 - a sample cup holder (41) having a plurality of chambers, each of which is apt to receive and hold the lower part of a sample cup (51-69) preventing rotation thereof,
 - a plurality of sample cups (51-69), each of which is closed with a removable screwable cap and the lower part of which is inserted in one of said chambers of the sample cup holder (41),

the outer wall of each of said cups (51-69) having a zone the shape of which is apt to cooperate with a corresponding zone of the inner surface of the chamber of the sample cup holder (41) to prevent rotation of the sample cup (51-69) inserted in said chamber,
said screwable cap having a recess located in the top and central part of the cap, said recess comprising a slot which extends along the length axis of the sample cup and which ends in two annular channel segments which extend in opposite angular directions with respect to the length axis of the sample cup,

 - a gripper (11) movable in three orthogonal directions by a transport device, said gripper (11) comprising a rotatable gripper tool (21) which has an end part having a shape and dimensions which match the shape and dimensions of the recess of the cap in such a way that the end part of the gripper tool (21) can enter through the slot of the cap's recess and by rotation enter into and engage the annular channel segments of said recess,
 - a transport device for moving said gripper (11) in said three orthogonal directions and for positioning and rotating said gripper tool (21) of a predetermined angle within said recess of the cap of a sample cup (51-69).
- A method for automatically handling sample cups closed with a screwable cap (34) in a system wherein portions of biological samples contained in primary sample tubes have to be automatically pipetted into and from said sample cups, said method comprising transporting a sample cup (31) by means of a transportable gripper (11) which includes a rotat-

able gripper tool (21) apt to enter a recess (35, 36, 37) of said cap (34), said transporting being effected by positioning said gripper tool (21) in said recess (35, 36, 37),

by rotating said gripper tool (21) within said recess (35, 36, 37) with respect to said sample cup (31) until it engages and locks into said recess (35, 36, 37), and

by transporting the gripper (11) and thereby the sample cup (31) from a first position to a second position.

5

10

4. A method for automatically handling sample cups closed with a screwable cap in a system wherein portions of biological samples contained in primary sample tubes have to be automatically pipetted into and from said sample cups, said method comprising removing the cap (34) of a sample cup (31) by means of a transportable gripper (11) which includes a rotatable gripper tool (21) apt to enter a recess (35, 36, 37) of said cap (34), said removing being effected

15

20

by positioning said gripper tool (21) in said recess (35, 36, 37), and

by rotating said gripper tool (21) within said recess (35, 36, 37) in a first sense with respect to said sample cup (31), thereby unscrewing the cap (34) and removing it from the sample cup (31).

25

30

5. A method for automatically handling sample cups closed with a screwable cap (34) in a system wherein portions of biological samples contained in primary sample tubes have to be automatically pipetted into and from said sample cups, said method comprising replacing the cap (34) of a sample cup (31) by means of a transportable gripper (11) which includes a rotatable gripper tool (21) apt to enter a recess (35, 36, 37) of said cap (34), said replacing being effected

35

40

by positioning said gripper tool (21) in said recess (35, 36, 37), and

45

by rotating said gripper tool (21) within said recess (35, 36, 37) in a second sense with respect to said sample cup (31), said second sense being opposite to said first sense, thereby screwing the cap (34) and replacing it on the sample cup (31).

50

6. A sample cup (31) comprising a removable screwable cap (34) which has a recess located in the top and central part of the cap, said recess comprising a slot (37) which extends along the length axis of the sample cup (31) and which ends in two annular channel segments (35, 36) which extend in oppo-

55

site angular directions with respect to the length axis of the sample cup (31), and

an outer wall (32) having a zone (33) which is adapted to cooperate with a corresponding zone of the inner surface of a chamber of a sample cup holder in order to prevent rotation of the sample cup (31) when the lower part thereof is inserted in that chamber.

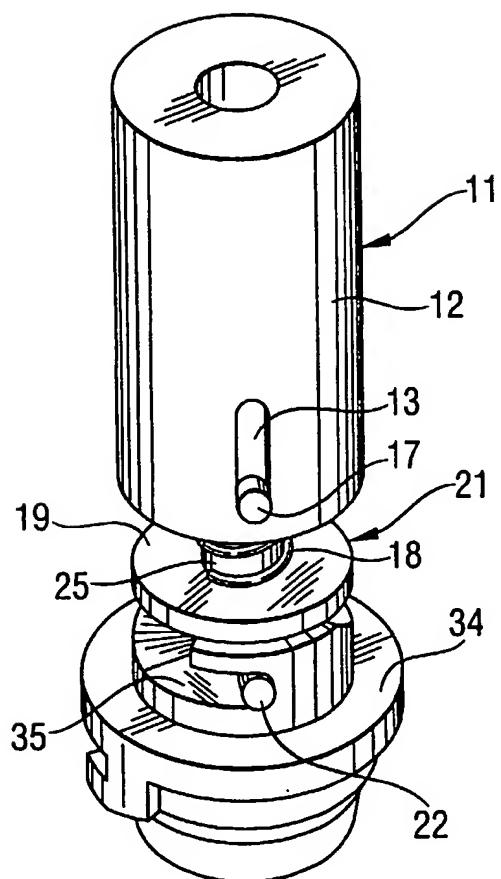


Fig. 1

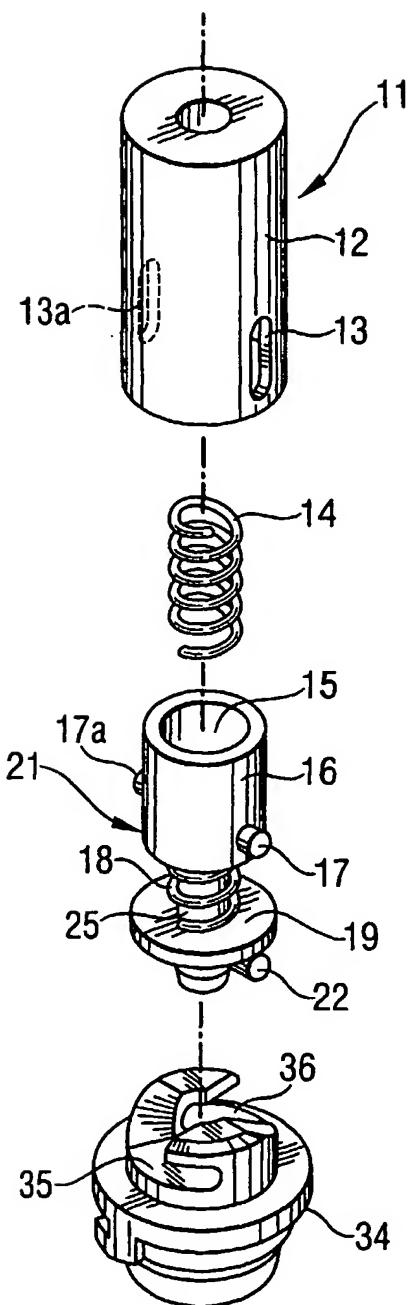


Fig. 2

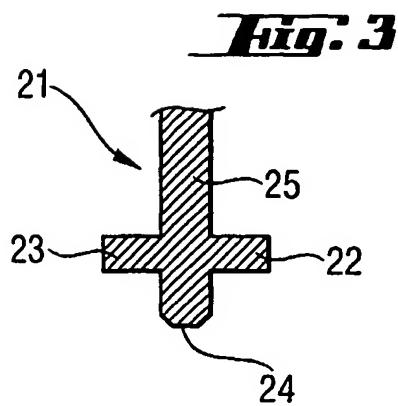


Fig. 3

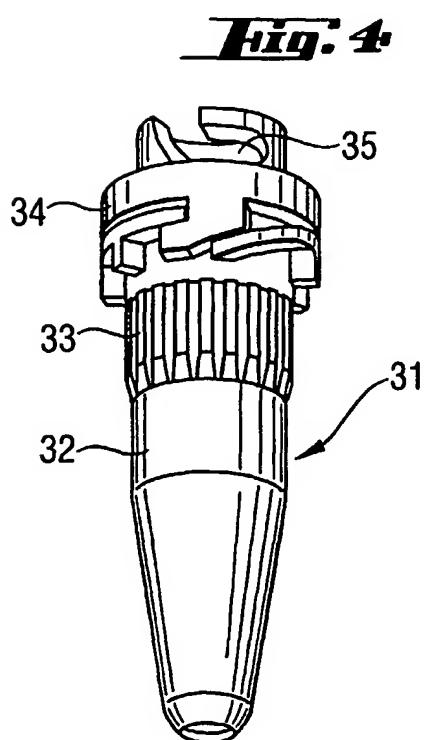


Fig. 4

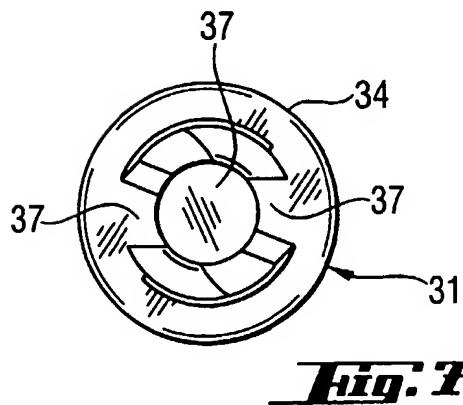
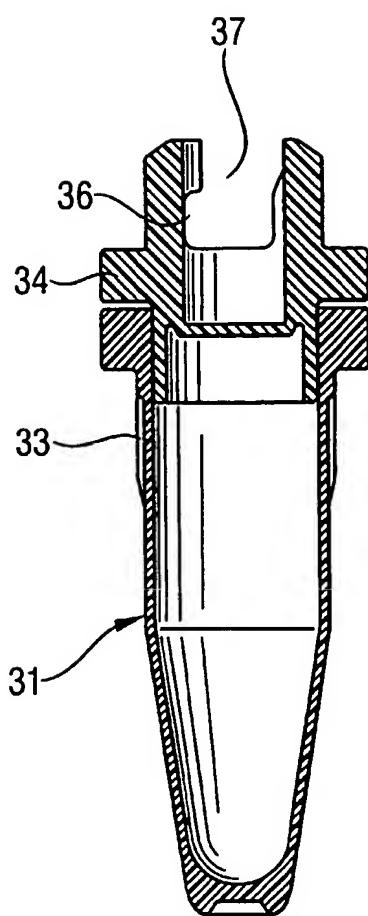
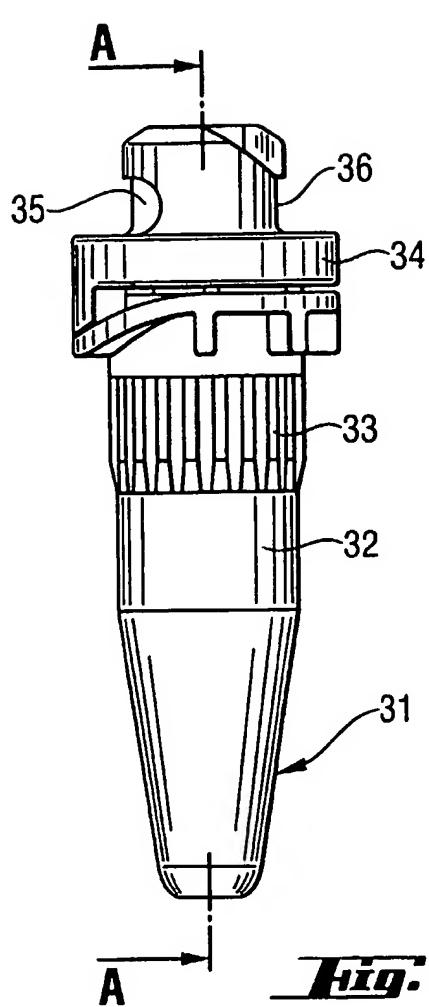
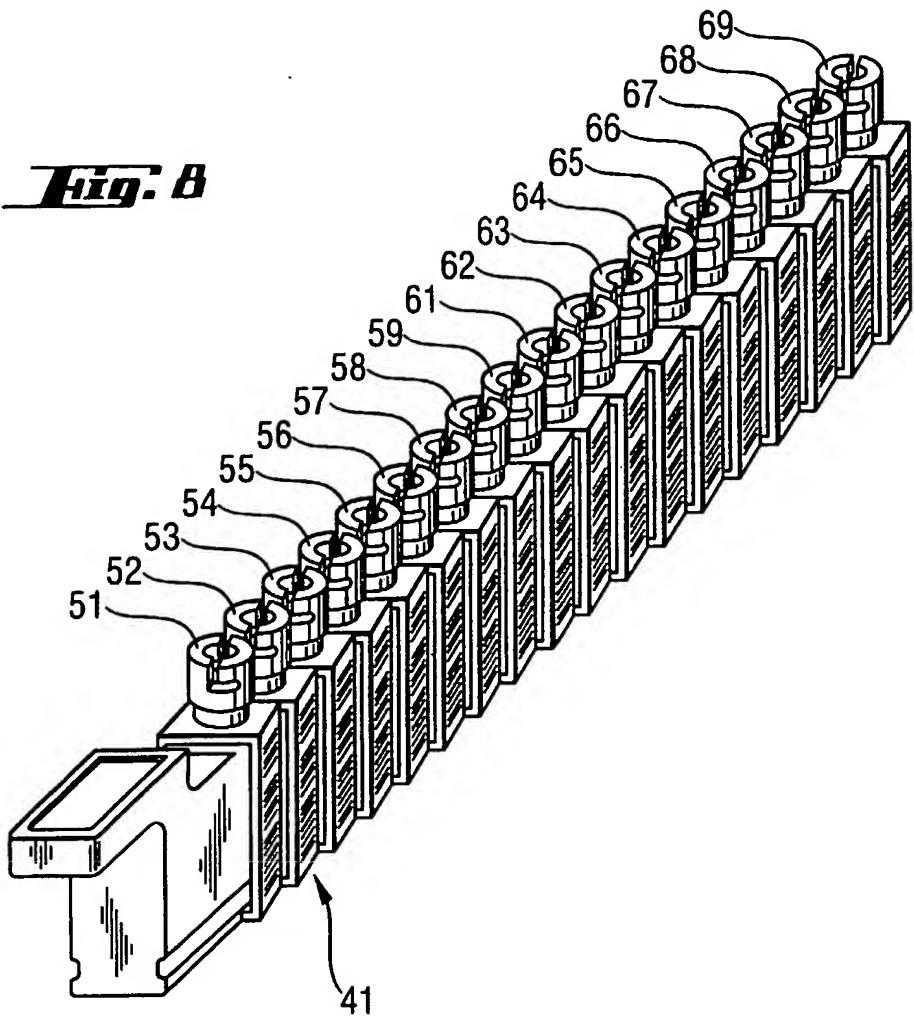


Fig. 8



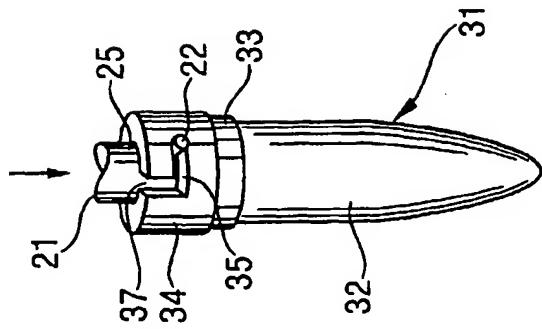


Fig. 12

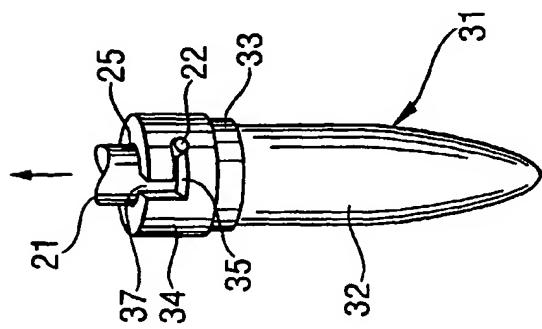


Fig. 11

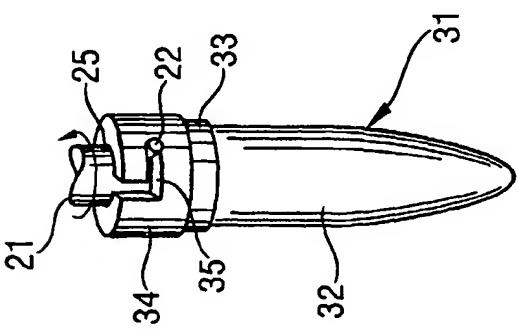


Fig. 10

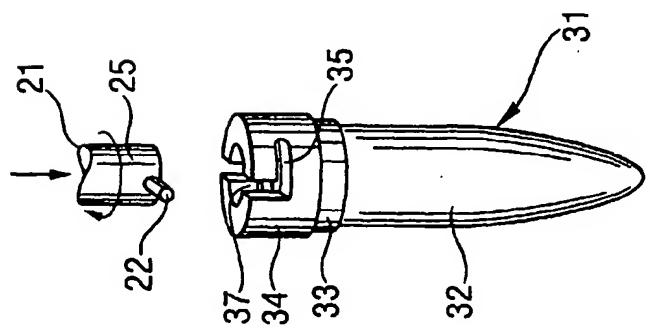


Fig. 9

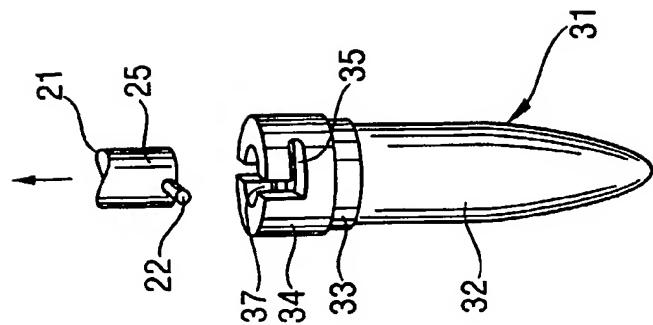


Fig. 16

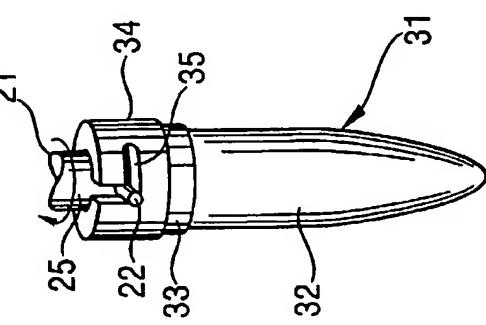


Fig. 15

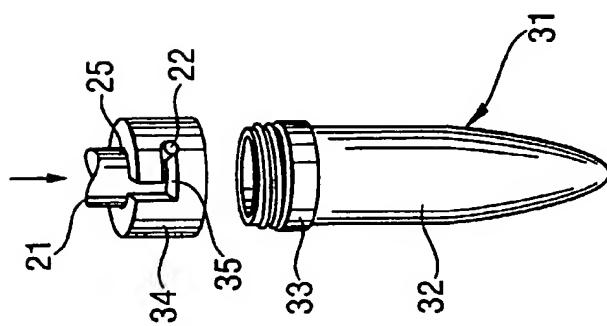


Fig. 14

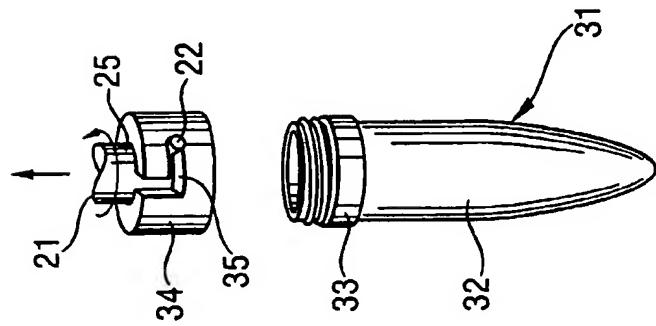


Fig. 13



European Patent
Office

EUROPEAN SEARCH REPORT

Application Number

EP 98 81 0932

DOCUMENTS CONSIDERED TO BE RELEVANT			CLASSIFICATION OF THE APPLICATION (Int.Cl.6)
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	
A	EP 0 676 643 A (BOEHRINGER MANNHEIM GMBH) 11 October 1995 * column 2, line 27 - line 53 * * column 3, line 25 - line 48 * * column 4, line 37 - column 5, line 21 * * column 6, line 15 - column 7, line 41 * * column 10, line 5 - line 35 * * column 11, line 50 - column 12, line 14; figures 2,5,6 * ---	1,3-5	G01N35/04 G01N35/00 B67B7/02 B65D39/16
A	US 5 533 407 A (BESNIER JOSEPH) 9 July 1996 * column 2, line 3 - column 3, line 22; figures 1-6 * * column 7, line 18 - line 61 * * column 9, line 32 - column 10, line 52; figures 1-6 * ---	1,3-5	
A	GB 2 273 493 A (CANYON EUROPE LTD) 22 June 1994 * page 2, line 2 - line 11 * * page 3, line 1 - line 10 * * page 4, line 16 - page 5, line 4 * * figures 1-3 * ---	1,3-5	
A	PATENT ABSTRACTS OF JAPAN vol. 015, no. 513 (M-1196), 26 December 1991 & JP 03 226485 A (SHIMADZU CORP), 7 October 1991 * abstract; figure 1 * ---	1,4 -/-	G01N B65D B67B
The present search report has been drawn up for all claims			
Place of search	Date of completion of the search	Examiner	
THE HAGUE	8 January 1999	Koch, A	
CATEGORY OF CITED DOCUMENTS			
X : particularly relevant if taken alone	T : theory or principle underlying the invention		
Y : particularly relevant if combined with another document of the same category	E : earlier patent document, but published on, or after the filing date		
A : technological background	D : document cited in the application		
O : non-written disclosure	L : document cited for other reasons		
P : intermediate document	& : member of the same patent family, corresponding document		



European Patent
Office

EUROPEAN SEARCH REPORT

Application Number
EP 98 81 0932

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int.Cl.6)
A	US 5 578 494 A (CLARK FREDERIC L ET AL) 26 November 1996 * column 14, line 3 - line 17 * * column 19, line 22 - line 39 * * column 43, line 48 - column 46, line 6 * * column 48, line 6 - column 49, line 29 * * figures 29-39 *	1-4	
A	US 5 366 896 A (MARGREY KEITH S ET AL) 22 November 1994 * column 2, line 28 - line 34 * * column 3, line 66 - column 4, line 7 * * column 4, line 24 - line 44 * * column 5, line 20 - line 60 * * column 12, line 4 - line 46 * * column 24, line 1 - column 25, line 15; figures 1-8,12-21 * * column 26, line 11 - column 30, line 6 *	1-3	
			TECHNICAL FIELDS SEARCHED (Int.Cl.6)
The present search report has been drawn up for all claims			
Place of search THE HAGUE	Date of completion of the search 8 January 1999	Examiner Koch, A	
CATEGORY OF CITED DOCUMENTS		T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons S : member of the same patent family, corresponding document	
X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document			

ANNEX TO THE EUROPEAN SEARCH REPORT
ON EUROPEAN PATENT APPLICATION NO.

EP 98 81 0932

This annex lists the patent family members relating to the patent documents cited in the above-mentioned European search report.
 The members are as contained in the European Patent Office EDP file on
 The European Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

08-01-1999

Patent document cited in search report		Publication date		Patent family member(s)		Publication date
EP 0676643	A	11-10-1995		DE 4412286 A		12-10-1995
				JP 7287019 A		31-10-1995
				US 5846489 A		08-12-1998
US 5533407	A	09-07-1996		FR 2711243 A		21-04-1995
				DE 69401893 D		10-04-1997
				DE 69401893 T		18-09-1997
				EP 0649149 A		19-04-1995
				JP 7191045 A		28-07-1995
GB 2273493	A	22-06-1994		AU 5705094 A		04-07-1994
				WO 9413547 A		23-06-1994
US 5578494	A	26-11-1996		US 5376313 A		27-12-1994
				AU 7843194 A		10-04-1995
				CA 2172363 A		31-03-1995
				EP 0720747 A		10-07-1996
				JP 9503060 T		25-03-1997
				WO 9508774 A		30-03-1995
				US 5646049 A		08-07-1997
				US 5635364 A		03-06-1997
				US 5605665 A		25-02-1997
				US 5575978 A		19-11-1996
				US 5627522 A		06-05-1997
				US 5536471 A		16-07-1996
				US 5507410 A		16-04-1996
				US 5610069 A		11-03-1997
				US 5762878 A		09-06-1998
				AU 3929093 A		08-11-1993
				AU 3934393 A		08-11-1993
				AU 3934993 A		08-11-1993
				AU 3935093 A		08-11-1993
				AU 3967793 A		08-11-1993
				AU 3968093 A		08-11-1993
				CA 2129245 A		14-10-1993
				CA 2129246 A		14-10-1993
				CA 2129367 A		14-10-1993
				CA 2129368 A		14-10-1993
				CA 2132959 A		14-10-1993
				CA 2132960 A		14-10-1993
				EP 0755519 A		29-01-1997
				EP 0634016 A		18-01-1995
				EP 0637283 A		08-02-1995
				EP 0746769 A		11-12-1996
				EP 0632894 A		11-01-1995
				EP 0632896 A		11-01-1995

EPO FORM P0459

For more details about this annex : see Official Journal of the European Patent Office, No. 12/82

**ANNEX TO THE EUROPEAN SEARCH REPORT
ON EUROPEAN PATENT APPLICATION NO.**

EP 98 81 0932

This annex lists the patent family members relating to the patent documents cited in the above-mentioned European search report.
 The members are as contained in the European Patent Office EDP file on
 The European Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

08-01-1999

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
US 5578494 A		JP 7505473 T JP 7505474 T JP 2769245 B JP 7505475 T JP 7505343 T JP 7505476 T JP 7506184 T WO 9320440 A WO 9320444 A WO 9320443 A WO 9319928 A WO 9320441 A WO 9320450 A US 5358691 A US 5540890 A US 5482861 A	15-06-1995 15-06-1995 25-06-1998 15-06-1995 15-06-1995 15-06-1995 06-07-1995 14-10-1993 14-10-1993 14-10-1993 14-10-1993 14-10-1993 25-10-1994 30-07-1996 09-01-1994
US 5366896 A	22-11-1994	US 5631844 A	20-05-1997

For more details about this annex : see Official Journal of the European Patent Office, No. 12/82